

TM200N TM220N

TM260N

TM280N

**RM200N** 

**RM220N** 

**RM260N** 

**RM280N** 



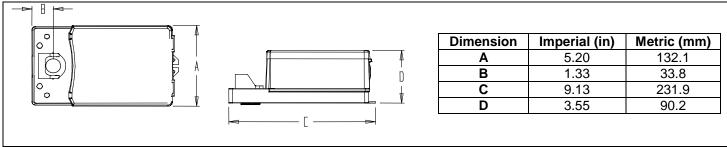
### Features:

- Clutch for manual adjustments.
- Maintenance free.
- Position indicator.
- Control signal fully programmable.
- Brushless DC driven motor.
- Fail safe by Enerdrive System<sup>1</sup> (on model 260 & 280).
- Auxiliary switches (on model 260 & 280).

Technical Data	TM200N	TM220N	TM260N	TM280N	RM200N	RM220N	RM260N	RM280N
Auxiliary switches	No	Yes (2)	No	Yes (2)	No	Yes (2)	No	Yes (2)
Fail safe - Enerdrive	Ν	lo	Y	es	Ν	lo	Y	es
Power consumption	20 VA		45 VA Peak, 20 VA		30 VA		50 VA Peak, 30 VA	
Torque	180 in.lb. [20 Nm] at rated voltage 360 in.lb. [40 Nm] at rated voltage			е				
Running time through 90º	40 to 50 sec torque dependant							
Power supply	28 to 32 Vdc or 22 to 26 Vac, 220 to 250 Vac 50/60Hz							
Feedback	4 to 20 mA or 2 to 10 Vdc adjustable							
Electrical connection	18 AWG [0.8 mm <sup>2</sup> ] minimum							
Inlet bushing	2 inlet bushing of 7/8 in [22.2 mm]							
Control signal	Analog, Digital or PWM programmable (factory set with analog control signal)							
Angle of rotation	0 to 90 degrees, electronically adjustable (factory set with 90° stroke)							
Direction of rotation	Reversible, Clockwise (CW) or Counterclockwise (CCW) (factory set with CW direction)							
Operating temperature	0°F to 122°F [-18°C to 50°C]							
Storage temperature	-22°F to 122°F [-30°C to 50°C]							
Relative Humidity	5 to 95 % non condensing.							
Weight	5 lbs. [2.3 kg] 8 lbs. [3.5 kg]							

### Warning: Do not press the clutch when actuator is powered

### Dimensions



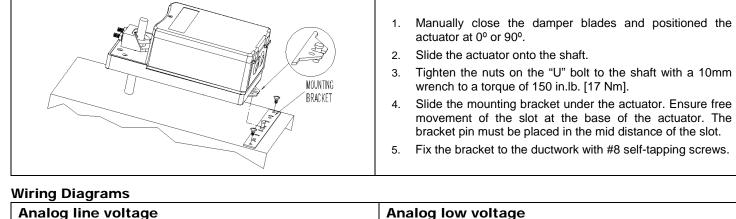
### Caution

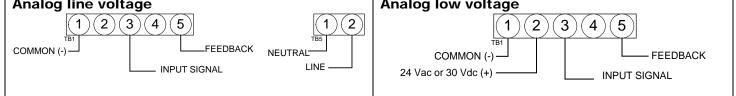
We strongly recommend that all Neptronic<sup>®</sup> products be wired to a separate transformer and that transformer shall service only Neptronic<sup>®</sup> products. This precaution will prevent interference with, and/or possible damage to incompatible equipment. When multiple actuators are wired on a single transformer, polarity must be observed. Long wiring runs create voltage drop which may affect the actuator performance.

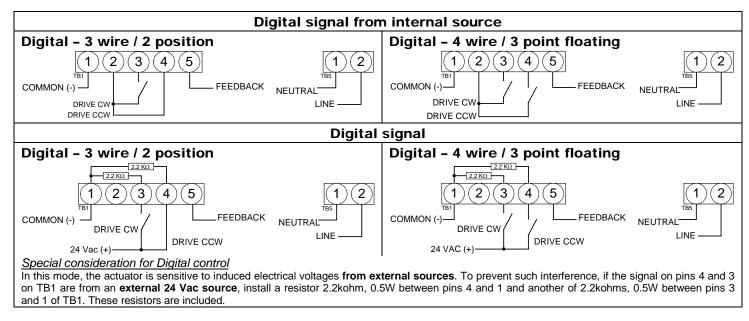
<sup>1</sup> Enerdrive System U.S.A. Patent #5,278,454



# **Mechanical Installation**





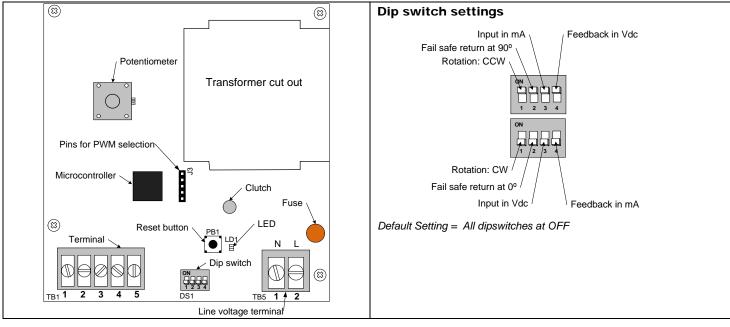


# Input Signal and Feedback setup

	Input Signal	Feedback		
Analog Mode	Input Signal is set with Dipswitch # 3 DS1-3 at OFF = 2 - 10Vdc (default setting) DS1-3 at ON = 4 - 20mA	Feedback is set with Dipswitch #4		
Digital & PWM Mode	No Input Signal Setting DS1-3 MUST be at OFF	DS1-4 at OFF = $4 - 20$ mA (default setting) DS1-4 at ON = $2 - 10$ Vdc		

# TM200/220/260/280N RM200/220/260/280N

#### PC Board



## Stroke adjustment - No control signal change

- 1. Apply power and, WAIT FOR LED TO BE OFF (around 10 seconds).
- 2. Press and release the reset button to start the auto-stroke process. The LED should be illuminated.
  - First option:

The actuator will then travel in both directions to find its limit and position itself according to the demand. The LED will extinguish, the process is complete.

 Second option: When the desired start position is reached, press and release the reset button. The actuator will now go the end position. (you can also press and release the reset button when It's reaches the end position) The LED will extinguish, the process is complete.

## Programming - Change of control signal & PWM pulse setting

- 1. Remove power and put all dip switches "OFF". (factory preset).
- 2. Apply power and, within 10 seconds, press and release the reset button. The LED should be blinking.
- 3. Select the control signal with dip switches:

	Digital or Analog Modes	PWM Mode
Move switch <b><u>No1</u></b> "ON" and then "OFF".	Digital (On/Off or 3 point floating)	5 sec. pulse (factory preset)
Move switch <u>No2</u> "ON" and then "OFF".	<u>Analog</u> (Default)	25 sec. pulse

4. Stroke adjustment section above.

# RM200/220/260/280N

# **Enabling or disabling PWM mode**

1.	Remove power supply to actuator					
2.	2. Install jumper between pin 3 & 4 of J3				Pin #1 ——— မ်ာ	
3.	Select the	desired act	ion using the dipswitches (	DS1):		
	DS1-1 DS1-2 Action			Pin #2 / \		
	OFF	ON	Enable PWM Mode			
	ON	OFF	Disable PWM Mode		Pin #3	
4.	4. Re-apply power supply to actuator				FIII#3	
5. Wait 5 seconds						
6.	<ol><li>Remove power supply to actuator</li></ol>				Pin #4 /	
7.	7. Remove jumper between pin 3 & 4 of J3, re-install it between pin 4 & 5.					
8.	8. Re-apply power supply to actuator				Pin #5	
	PWM is factory preset at 5 sec. pulse,				When not used for programming,	
	refer to programming section above to change pulse setting.				jumper is placed between pin 4 & 5	

# Zero and span calibration

This feature is applicable to analog control signal only.

- 1. Remove power and put all dip switches "OFF". (factory preset).
- 2. Apply power and, **within 10 seconds** press and **hold** the reset button until the LED blinks once. The Zero and span calibration process then start.
- 3. Release the reset button. The LED is now constantly illuminated.
- 4. Apply new minimum voltage. It can be any value between 0 to 7 Vdc, with an external 0 to 10 volt supply (ex: MEP).
- 5. Press and release the reset button to memorize the new minimum voltage. The LED blinks.
- Apply new maximum voltage.
  It can be any value between 3 to 10 Vdc, this value should be greater than the new minimum value.
- 7. Press and release the reset button to memorize the new maximum voltage. The LED blinks. The Zero and span calibration process is complete.

Note: To reset zero and span to 2 to 10 Vdc (factory value). You just have to re-select the analog control signal mode, see Programming.

### Wiring Diagrams for auxiliary switches (on model 220 & 280)

BLACK LOWER COMMON	
RED LOWER CLOSED 10-90°	Auxiliary switch rating:
GREEN LOWER CLOSED 0-10°	5 Amp resistive, 250 Vac
BROWN UPPER COMMON	
WHITE UPPER CLOSED 0-80°	
BLUE UPPER CLOSED 80-90°	

